

Design of control circuit for terrain robot

Vu Van Manh

Abstract: This topic focuses on designing an advanced control circuit for terrain robots to meet the demands of searching, collecting information, and performing tasks in complex environments. Through a combination of theoretical research and experimentation, the topic will develop an efficient control system, enhancing the adaptability and reliability of terrain robots. The expected outcome of this topic is to create a practical application solution, contributing to the development of automation technology in the fields of geological industry and aerospace.

Keywords: control circuit, terrain robot, automatic system, complex environment, geological industry