

Building a Robot Arm Model Controlled by Smartphone

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Abstract: This topic aims to build an automation system based on robot control techniques via Smartphone, meeting the modern needs of society. Through theoretical and experimental research, the topic will describe the process of designing, implementing, and evaluating the system's performance. The expected result is to provide a flexible and efficient solution for industrial and civil activities, contributing to the development of the field of automation engineering.

Keywords: Smartphone-controlled robot, Automation engineering, Robot design, Experimental research, Technology application